

**Bilad Alrafidain University College**  
**Electric Power Techniques Engineering Department**  
**Control Systems Analysis**  
**Fourth Stage**  
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# **Control Systems Analysis**

## **Course Contents**

- Introduction to Control System.
- Transfer Function.
- Time Domain Analysis.
- Stability Analysis.
- Root Locus Method.
- Frequency Domain Analysis.
- Compensator Lead Network.
- Compensator Lag Network.
- PID Controllers.
- State Space Theory.
- State Space Representation.

## Lecture Three

# Transfer Function

## Poles & Zeros of a Transfer Function

**Poles :** Poles of a Transfer Function are the frequencies ( **Values of s** ) for which the **DENOMINATOR** of the Transfer Function becomes **ZERO**.

**Zeros :** Zeros of a Transfer Function are the frequencies ( **Values of s** ) for which the **NUMERATOR** of the Transfer Function becomes **ZERO**.

The general form of the Transfer Function :

$$T.F = \frac{(s - z_1)(s - z_2)(s - z_3) \dots (s - z_n)}{(s - p_1)(s - p_2)(s - p_3) \dots (s - p_n)}$$

$$\text{Zeros : } s = z_1, z_2, z_3, \dots z_n$$

$$\text{Poles : } s = p_1, p_2, p_3, \dots p_n$$

**Example 1 :** Find the Transfer Function of the system given by:

$$\frac{d^2y(t)}{dt^2} + 7 \frac{dy(t)}{dt} + 12y(t) = \frac{dx(t)}{dt} + 2x(t)$$

Where :  $x(t)$  is the input &  $y(t)$  is the output

$$\text{Transfer Function } G(S) = \frac{Y(S)}{X(S)} : \frac{\text{NUMERATOR}}{\text{DENOMINATOR}}$$

**Solution :** Taking Laplace Transform to the components of the Transfer Function:

$$s^2 \cdot Y(s) + 7s \cdot Y(s) + 12Y(s) = s \cdot X(s) + 2 \cdot X(s)$$

$$Y(s) \cdot [s^2 + 7s + 12] = X(s) \cdot [s + 2]$$

$$\frac{Y(s)}{X(s)} = \frac{s + 2}{s^2 + 7s + 12}$$

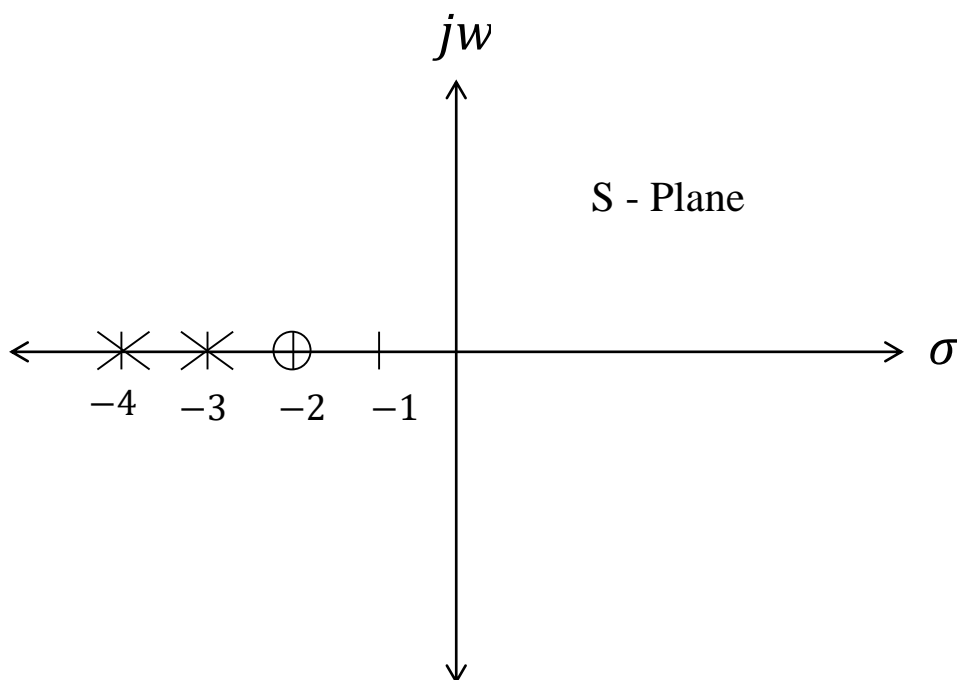
$$G(s) = \frac{s + 2}{(s + 3)(s + 4)}$$

Now the Poles & Zeros of the Transfer Function  $G(s) = \frac{s+2}{(s+3)(s+4)}$  are :

Zeros :  $s = -2$

Poles :  $s = -3, s = -4$

Let us now draw the ( Pole – Zero Diagram ) which is a plot on ( S-plane ) represents the locations of Poles and Zeros of a Transfer Function. In the ( Pole – Zero Diagram ) the Poles are represented by ( X ) and the Zeros represented by ( O ).



**Example 2 :** Find the Poles & Zeros for the following Transfer Function and then plot them on the ( S-Plane )?

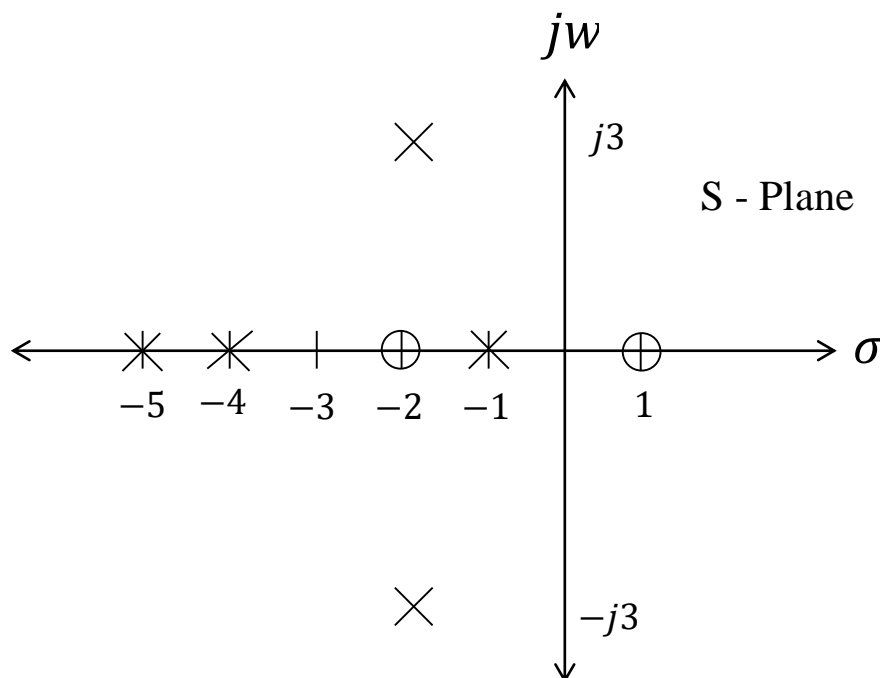
$$G(S) = \frac{(s + 2)(s - 1)}{(s + 1)(s + 4)(s + 5)(s + 2 + j3)(s + 2 - j3)}$$

**Solution :**

Zeros :  $s = -2, s = 1$

Poles :  $s = -1, s = -4, s = -5, s = -2 - j3, s = -2 + j3$

Let us now draw the ( Pole – Zero Diagram ) which is a plot on ( S-plane ) represents the locations of Poles and Zeros of a Transfer Function. In the ( Pole – Zero Diagram ) the Poles are represented by ( X ) and the Zeros represented by ( O ).



## Homework

Q1 / Find the Poles & Zeros for the following Transfer Function and then plot them on the ( S-Plane )?

$$G(S) = \frac{(2s + 6)(s + 2)}{s.(s + 1)(s + 4)}$$

$$G(S) = \frac{5}{s^3 + 6s^2 + 11s + 6}$$

$$G(S) = \frac{(s + 1.5)(s + 3 + j2)(s + 3 - j2)}{(s + 1)(s + 4)(s + 10)}$$